



## 메인보드 8M 연결 및 설치방법

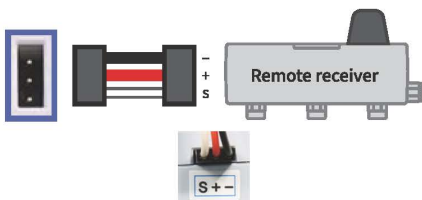


### 세그먼트창

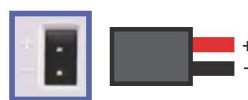
현재의 모드표시와 리모컨 설정을 위한 창



### Remote receiver sensor 연결 (F, 7 MODE)



### 모터 연결



### IR SENSOR (C MODE)



## 메인보드 모드설정방법

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- 1 전원스위치를 누른다.  
-전원 ON
- 2 모드스위치를 연속해서 누른다.  
-모드변경
- 3 선택하려는 모드에서 3초간 기다린다.  
-세그먼트 창이 3번 깜빡 거린다.
- 4 모드 설정 완료

## 메인보드 채널설정방법

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- 1 메인보드의 전원을 끈다.
- 2 모드스위치를 누른 상태에서 전원스위치를 켜다.
- 3 세그먼트 창에는 현재 저장된 채널이 표시된다.
- 4 모드스위치를 눌러 채널을 변경한다
- 5 선택하려는 번호에서 3초간 기다린다.  
-채널 설정이 완료되면 세그먼트 창이 깜빡 거린다.

# Wired Remote controller 유선리모컨

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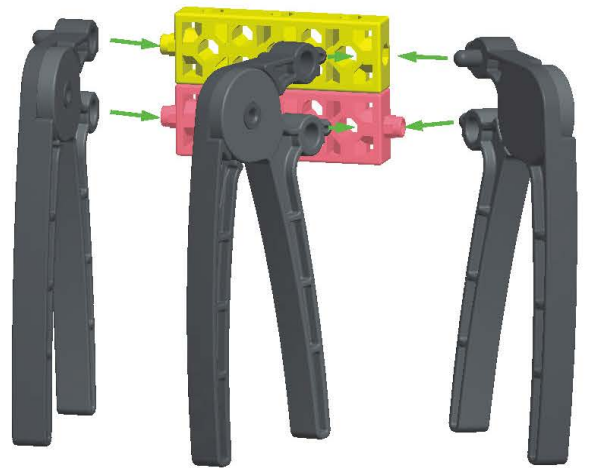


## 분리도구 사용법

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### Example 1

셀의 돌기와 돌기를 분리할 때



Example 1

Example 2

Example 3

### Example 2

셀의 홈과 홈을 분리할 때

### Example 3

셀의 홈과 돌기를 분리할 때

# wireless remote controller 유선 리모컨



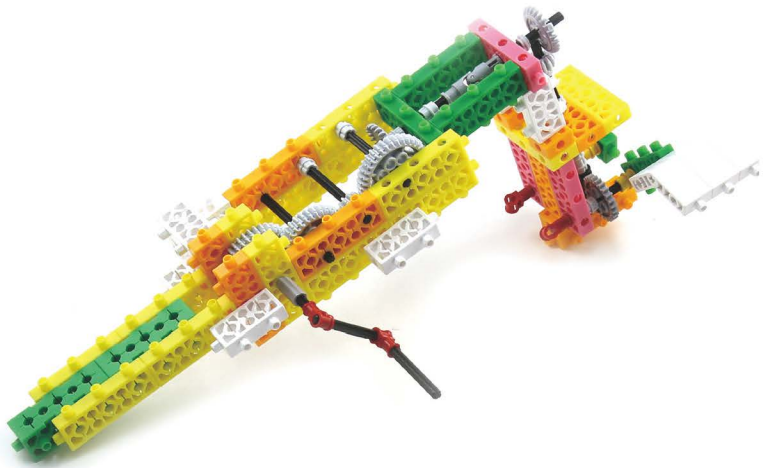
- 1 전원을 끈다.
- 2 (off)모드 스위치를 누른 상태에서 전원을 켜다.
- 3 (on)세그먼트창에 현재의 채널이 표시된다.
- 4 1번 or 3번 버튼을 눌러 채널을 변경한다.
- 5 4번 버튼을 눌러 채널설정완료.

※ 메인보드와 리모컨의 채널이 동일하게 설정되어야 합니다.

# 02



## 로봇팔

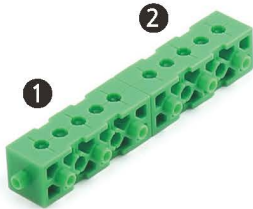


로봇팔 부품 리스트 | 구조물을 만들어 봅시다.

Diamond H8 (1)	Diamond H6 (1)	Rubi 8 (5)	Rubi 7 (5)	Rubi 6 (2)	Rubi 4 (12)	Rubi 2 (3)	Rubi 0 (2)	Mini 2 (8)	Mini 1 (3)	Curve (6)	36톱니동근 기어(3)	24톱니기어 (3)
크라운기어 (2)	12톱니동근 기어(4)	바벨기어 (1)	긴연결축 (2)	중간연결축 (8)	짧은연결축 (3)	8톱니기어 (4)	웜기어 (1)	유니버셜축 (1)	모터연결축 (2)	직각연결 (4)	A23 (1)	A45 (8)
A64 (4)												

# 1 ★★★

1-1

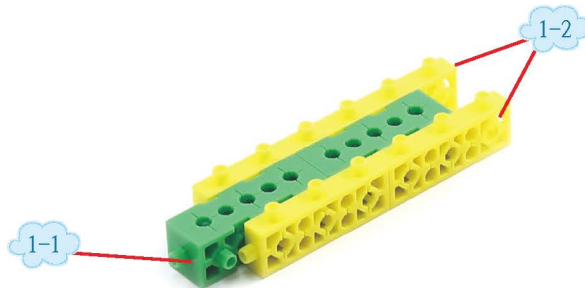


1-3

1-2

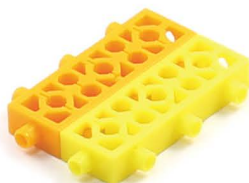
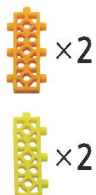


같은 모형 2개 만들어줍니다.



# 2 ★★★

2-1

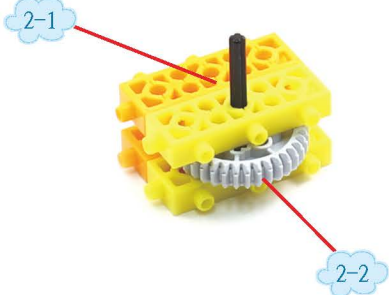


같은 모형 2개 만들어줍니다.

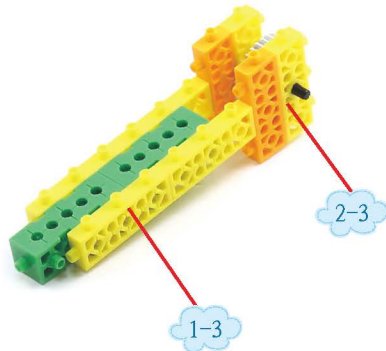
2-2



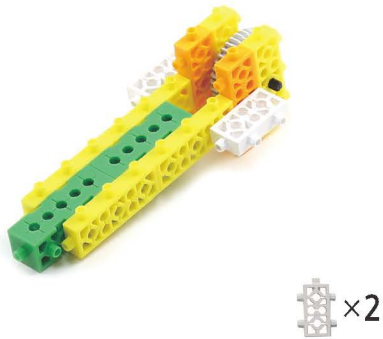
2-3



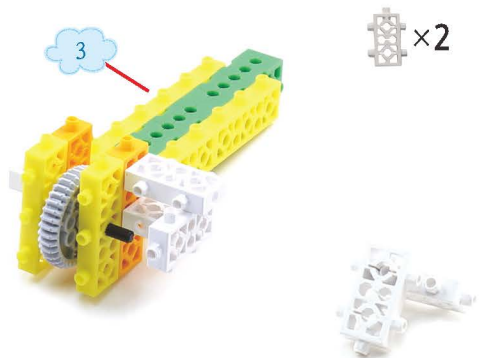
2-4



3☆☆☆









4☆☆☆



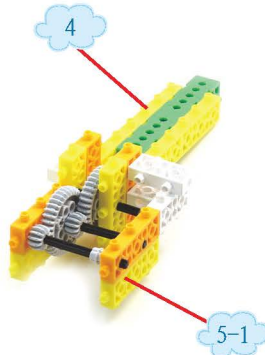
5☆☆☆

5-1

-  ×2
-  ×2
-  ×2
-  ×1
-  ×2
-  ×1

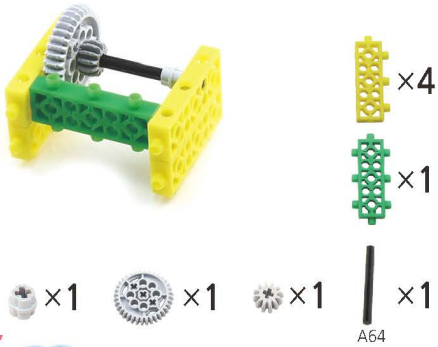


5-2

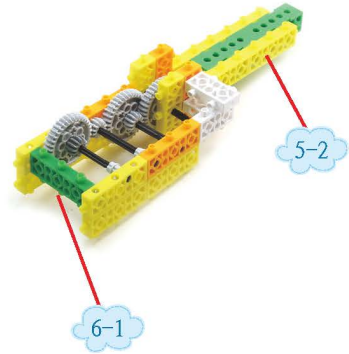


# 6\*\*\*\*

6-1



6-2



# 7\*\*\*\*

7-1

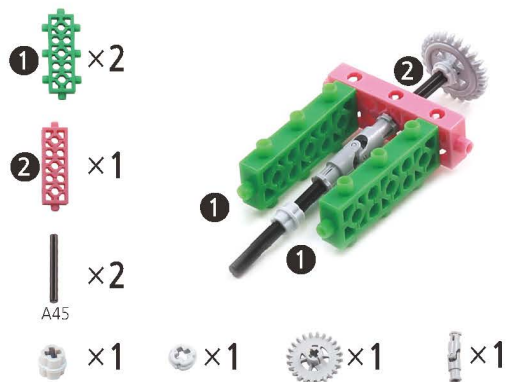


7-2

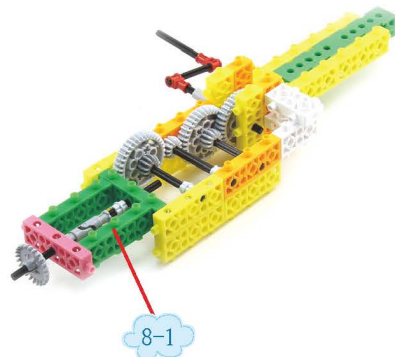


# 8\*\*\*\*

8-1



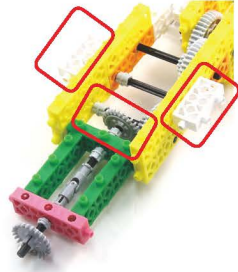
8-2









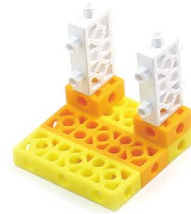
9\*\*\*

-  ×2
-  ×1
-  ×1



10\*\*\*

-  ×1
-  ×2
-  ×2
-  ×2



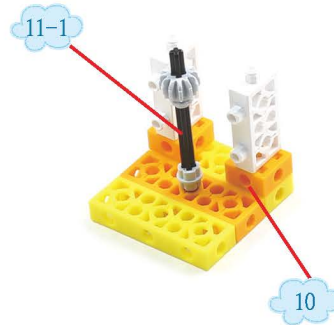
11\*\*\*

11-1

-  ×1
- A64
-  ×1
-  ×1
-  ×1



11-2



12\*\*\*







12-1

-  ×1

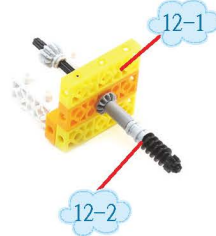


12-2






-  ×1
- A45
-  1 ×1
-  2 ×1
-  3 ×1
-  4 ×1
-  5 ×1

12-3



# 13\*\*\*

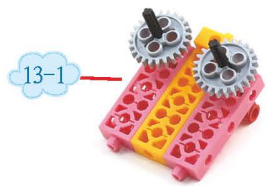
13-1

-  ×1
-  ×2
-  ×1



# 13-2

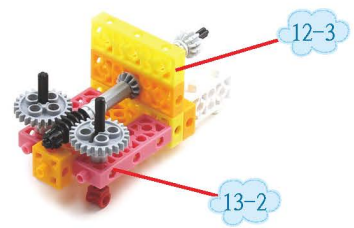
-  ×2  
A45
-  ×2
-  ×2
-  ×2



13-1



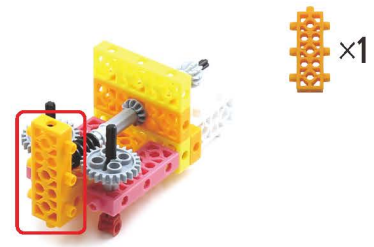
# 14\*\*\*



12-3

13-2




# 15\*\*\*



×1

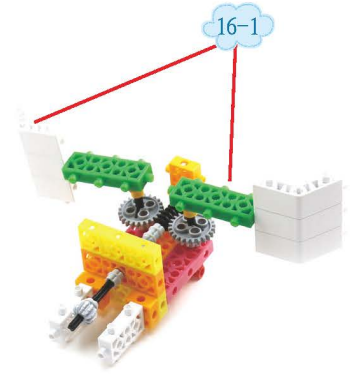
# 16\*\*\*

16-1

-  ×6
-  ×2
-  ×2

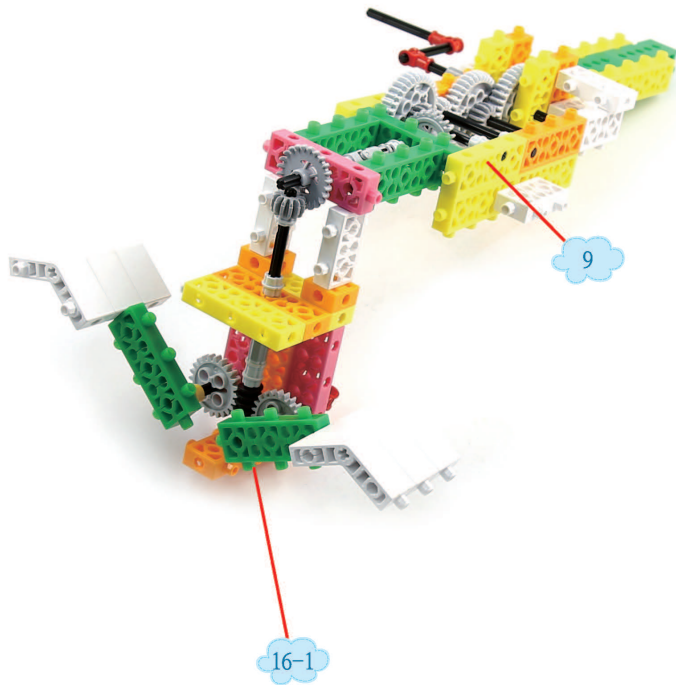


16-2



16-1

17 ★★★



complete

