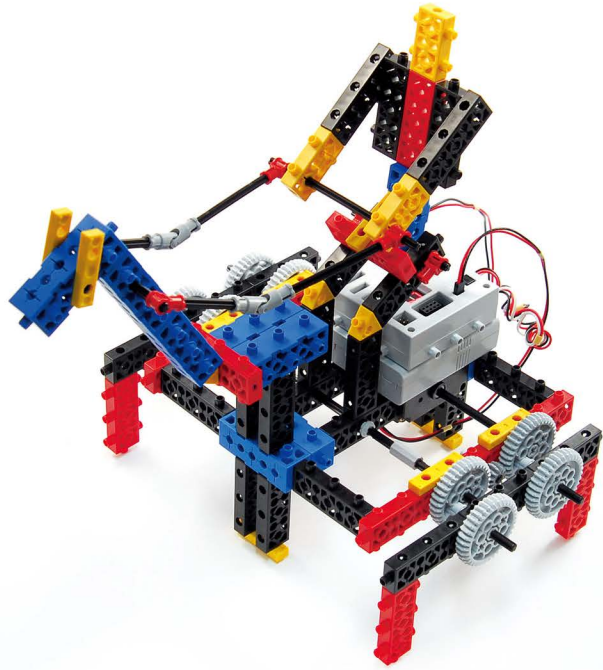


02



경마로봇

주변 경마장의 달리는 경마를 상상하여 동력을 이용한 로봇을 만들어 보세요.



경마로봇 부품리스트 | 구조물을 만들어 봅시다.

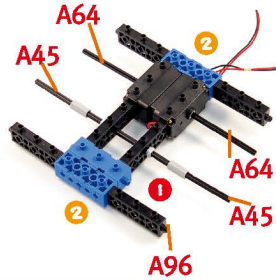
굵은돌기 수평셀 (5)	굵은 수평셀 (1)	굵은돌기 직각셀 (3)	8돌기셀 (2)	7돌기셀 (10)	4돌기셀 (12)	6돌기셀 (3)	2돌기셀 (8)	기본셀 (4)	2단셀 (3)	연결셀 (9)	삼각셀 (3)	12톱니동근 기어 (2)
36톱니동근 기어 (8)	짧은연결잭 (4)	중간연결잭 (6)	긴연결잭 (2)	직각연결잭 (6)	유니버설축 (2)	축23 (2)	축45 (8)	축64 (6)	축96 (2)	건전지6V 케이스 (1)	DC모터 (2)	MAIN (1)
연결잭 (1)												



경마로봇

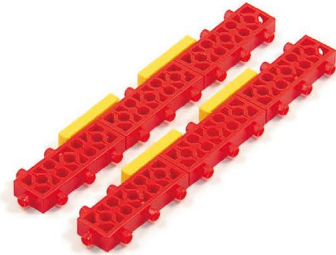
1 ★★★

- ① ×1
- ② ×2
- ×6
- ×2
- ×2
- ×2
- A96 ×1
- A64 ×2
- A45 ×2



2 ★★★

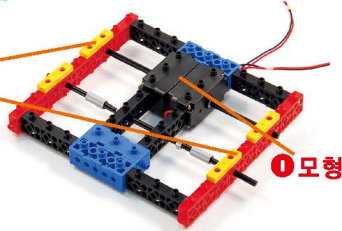
- ×6
- ×4



3 ★★★

3-1

②모형



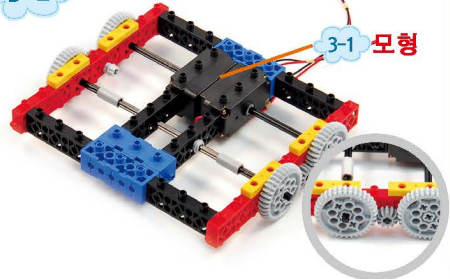
①모형

그림 1번과 2번에서 만든 모형을 조립합니다.

3-2

3-1 모형

- ×4
- ×2
- ×2
- A23
- ×2



4 ★★★

- ×4
- ×2



5 ★★★

밑모습

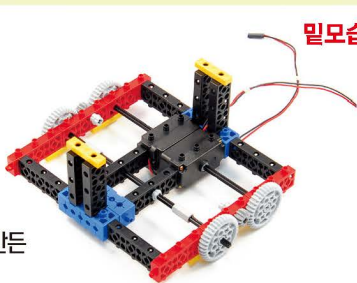
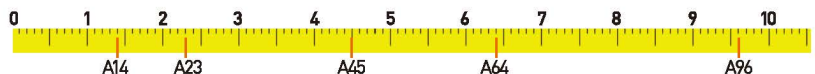
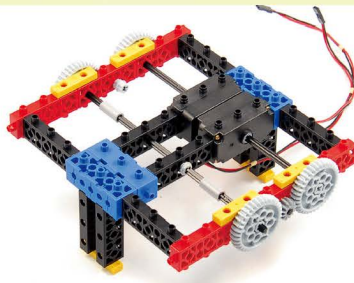


그림 3-2번과 4번에서 만든 모형을 조립합니다.

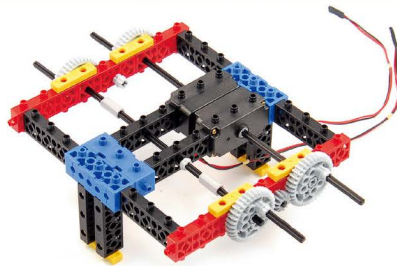
윗모습



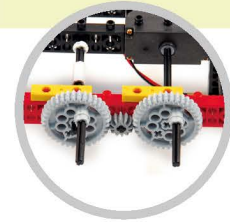


경마로봇

6 ★★★



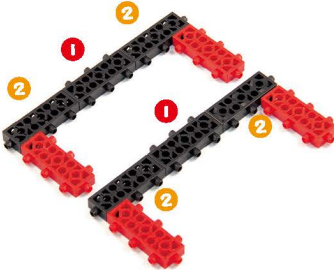
×4
A45 ×4



조립 위치 주의: 그림과 같은 위치에 조립해야만 동작이 유용합니다.

7 ★★★

① ×2
② ×4
×4



8 ★★★

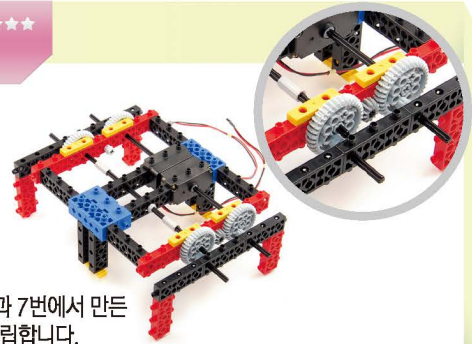
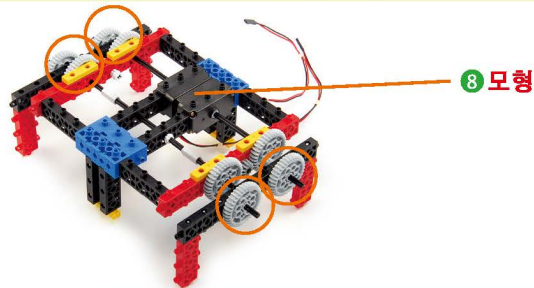


그림 6번과 7번에서 만든 모형을 조립합니다.

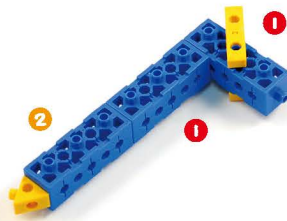
9 ★★★

×4



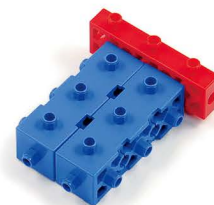
10 ★★★

① ×2
② ×1
×2 ×1



11 ★★★

×2
×1





경마로봇

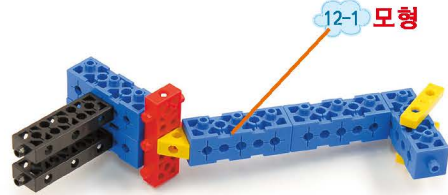
12***

12-1



그림 10번과 11번에서 만든 모형을 조립합니다.

12-2



13***

12-2 모형

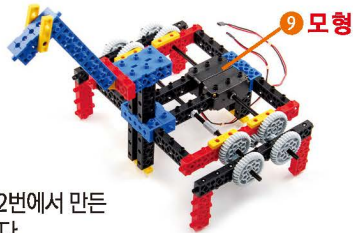
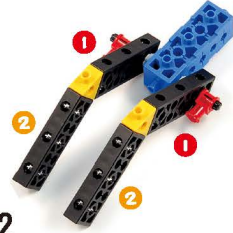


그림 9번과 12-2번에서 만든 모형을 조립합니다.

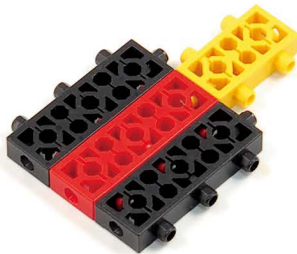
14***

14-1

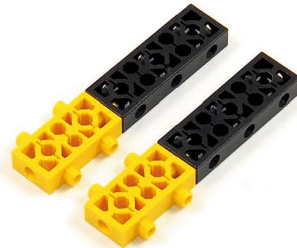


14***

14-2



14-3



14-4

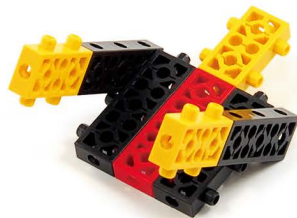


그림 14-2번과 14-3번에서 만든 모형을 조립합니다.

14-5

14-1 모형

14-4 모형

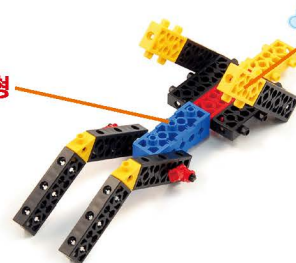


그림 14-1번과 14-4번에서 만든 모형을 조립합니다.



14****

14-6

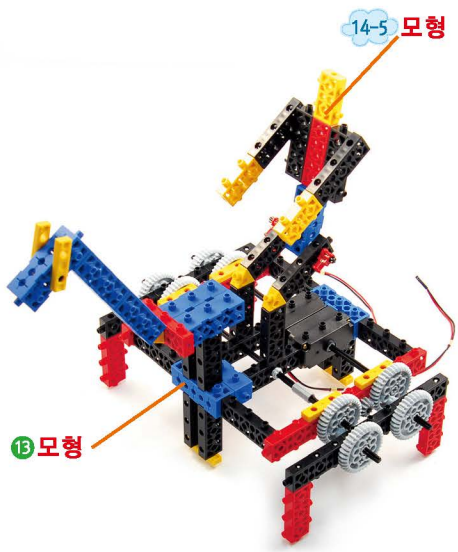
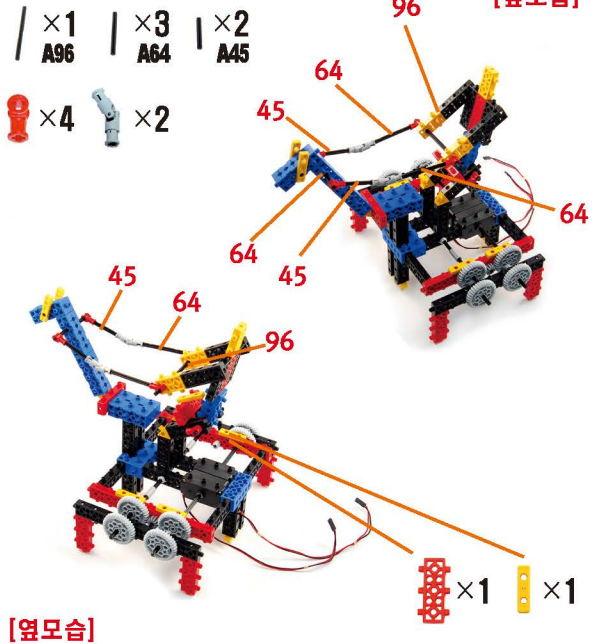


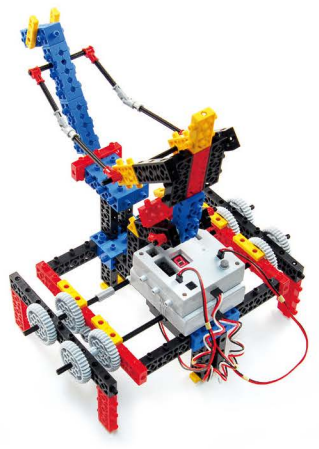
그림 13번과 14-5번에서 만든 모형을 조립합니다.

14-7

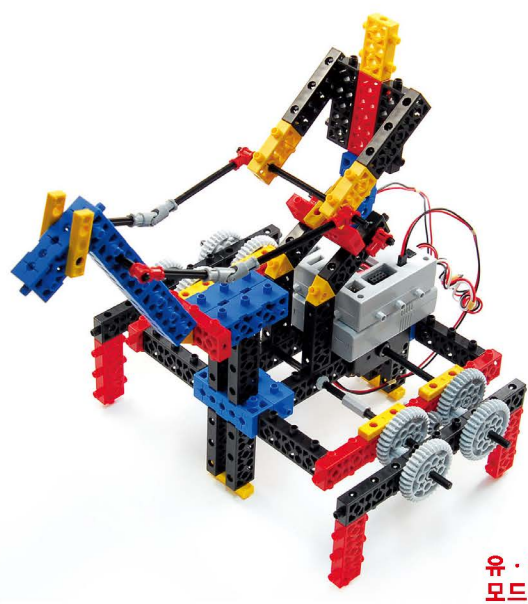


[옆모습]

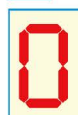
15****



 x1  x1  x1



※동작모드설정

ID 0	ID 1
	
전진	후진

유·무선 리모컨 사용 가능 모드(2번, F모드)