



오토바이

웜기어와 D.C모터를 이용하여 오토바이의 앞바퀴를 좌우로 돌려 움직이게 할 수 있는 로봇입니다. 다른 모형의 오토바이도 만들어보세요.



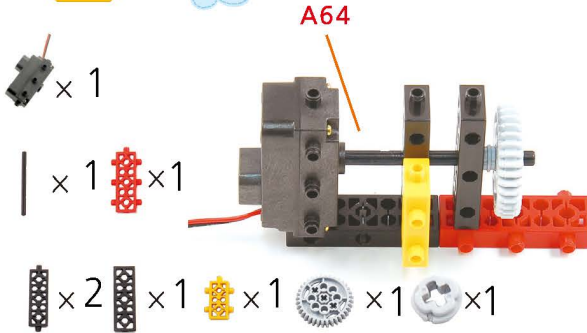
오토바이 부품리스트 | 구조물을 만들어 봅시다.

굵은 돌기 수평셀 (3)	굵은 돌기 수평셀 (1)	굵은 돌기 직각셀 (1)	굵은 직각셀 (6)	8돌기셀 (5)	7돌기셀 (7)	4돌기셀 (4)	6돌기셀 (6)	2돌기셀 (9)	기본셀 (6)	2단셀 (7)	1단셀 (1)	굴절셀 (2)
삼각셀 (7)	8톱니 기어(1)	24톱니 기어(2)	베벨기 어(2)	12톱니 기어(2)	36톱니 기어(5)	웜기어 (1)	짧은연결축 (4)	중간연결축 (8)	긴연결축 (1)	모터연결축 (1)	오프로드 바퀴(2)	축 14 (1)
축 64 (4)	축 96 (2)	배터리케 이스(1)	DC모터 (2)	유선리모컨 (1)	메인보드 (1)	연결축 (1)						

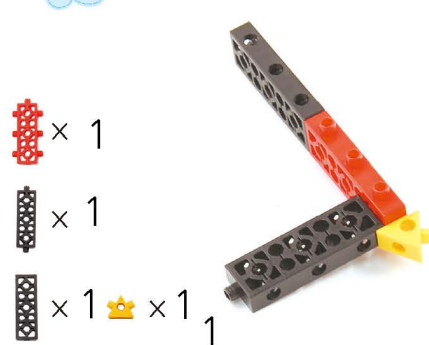


1 ★★★

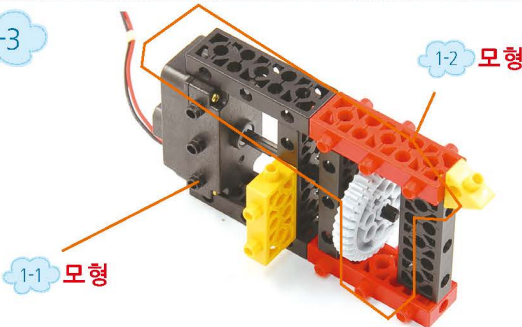
1-1



1-2



1-3



1-4



그림 1-1번과 1-2번에서 만든 모형과 조립합니다.

1-5

1-4 모형
(연결잭 조립 위치)

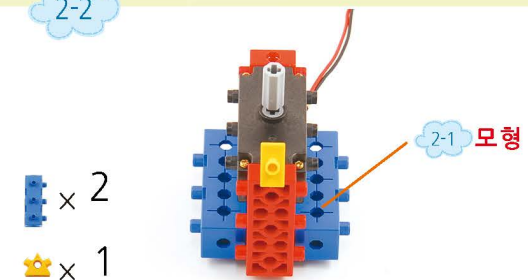


2 ★★★

2-1



2-2

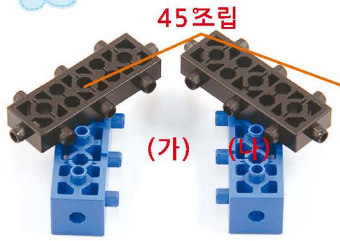




2***

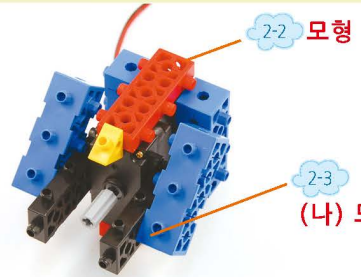
2-3

- × 2
- × 2



2-4

2-3 (가) 모형



3***

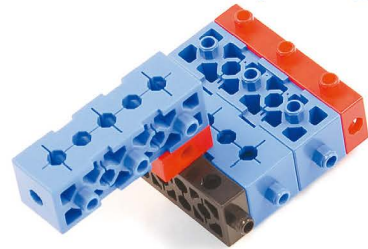
3-1

2-4 모형



3-2

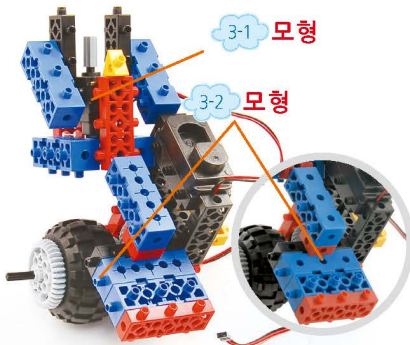
- × 1
- × 1
- × 1
- × 1
- × 1
- × 1



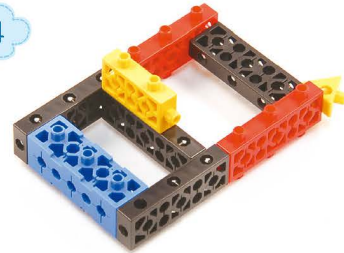
3-3

3-1 모형

3-2 모형



3-4



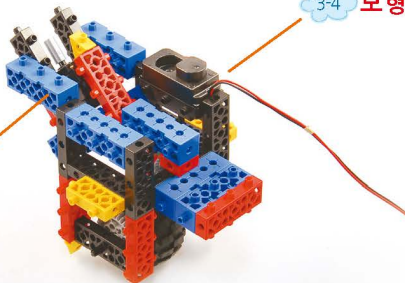
- × 1
- × 2
- × 2
- × 2
- × 1
- × 1

3-5

앞모습

3-4 모형

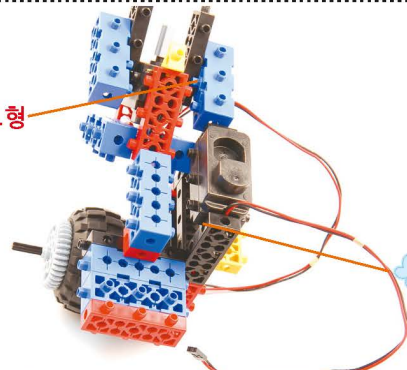
3-3 모형



측면

3-3 모형

3-4 모형



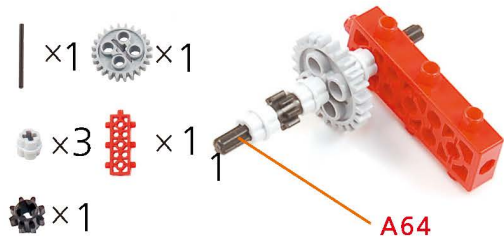


4***

4-1



4-2

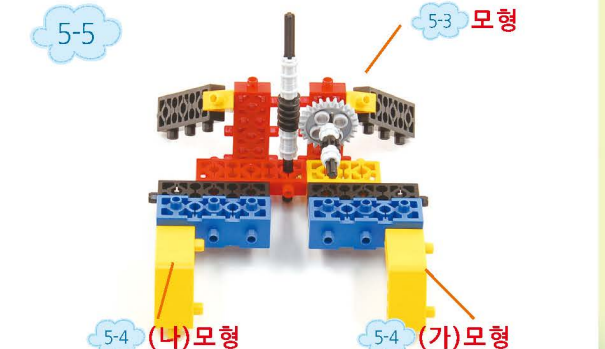
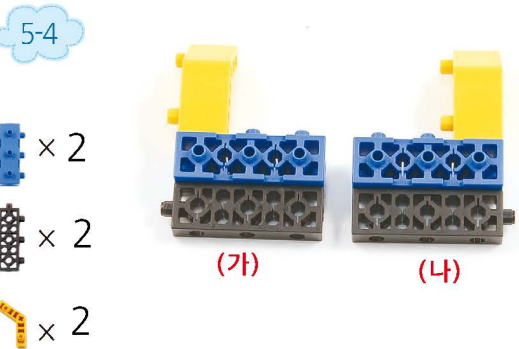
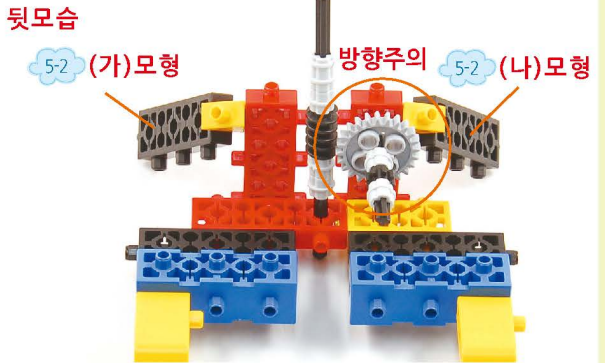
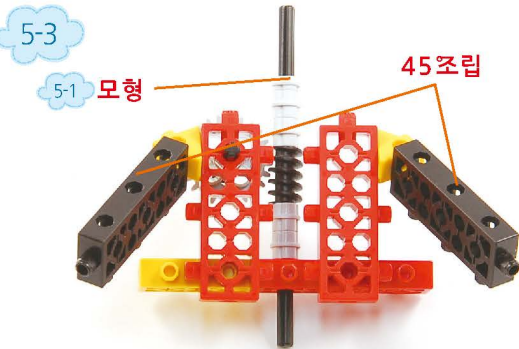
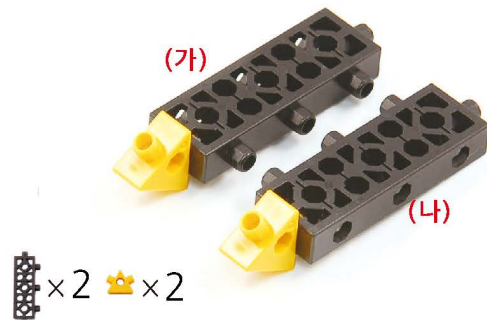


5***

5-1



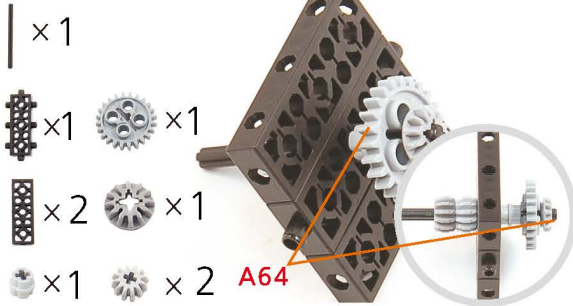
5-2



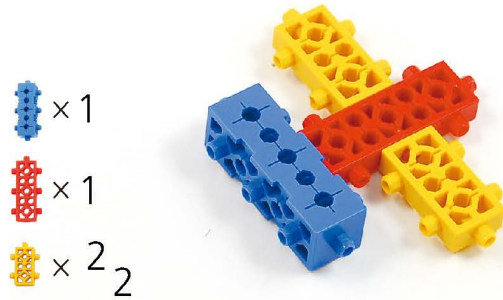


6***

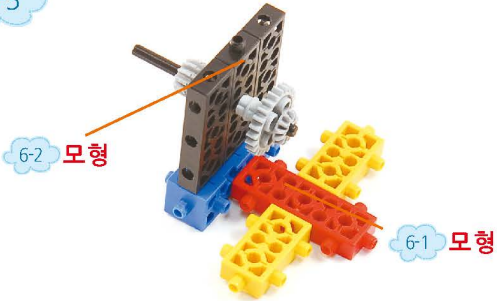
6-1



6-2



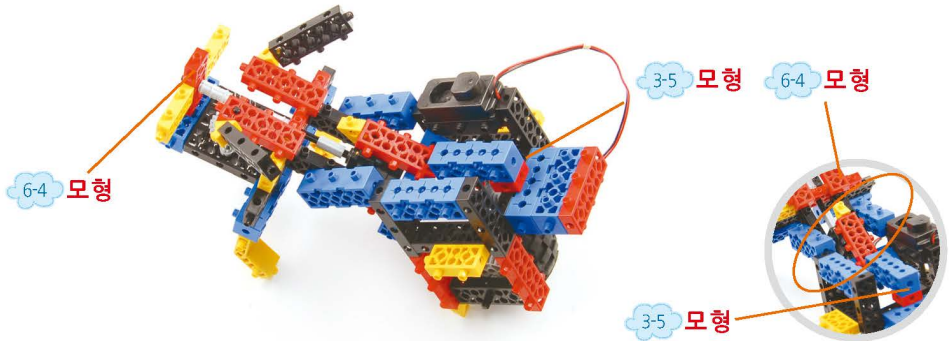
6-3



6-4



6-5



7***

7-1



7-2





7***

- × 1
- × 1
- × 1



7-4

7-3 모형

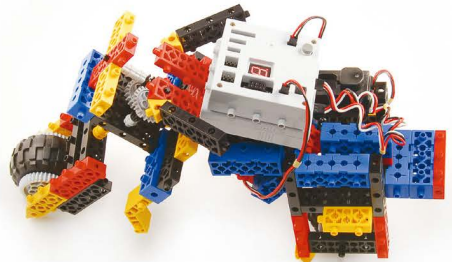
6-5 모형



8***

8-1

- × 1
- × 1
- × 1



메인보드 연결방법 및 설정

※ 동작모드설정



유선리모콘
연결포트

세그먼트창
모드를 표시하거나
리모콘을 아이디 설정시
상태를 표시하는 창

좌측
DC모터 커넥터

우측
DC모터 커넥터

전원스위치
On/Off

MODE설정
스위치

건전지 케이스 연결 커넥터

